

A Modification for the Viscosity Approximation Method for Fixed Point Problems in Hilbert Spaces

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Abstract: In this paper, we present a modification for the viscosity approximation method for fixed point problems of a nonexpansive mapping in Hilbert spaces. The modification removes a control condition of the viscosity approximation method. We establish a strong convergence theorem for the modified algorithm.

Key words: Nonexpansive mapping; Metric projection; Fixed point; Contraction; Viscosity approximation method

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1. Introduction

Let C be a nonempty closed convex subset of a real Hilbert space H . Recall that a self-mapping $f : C \rightarrow C$ is an α -contraction if there exists a constant $\alpha \in [0, 1)$ such that

$$\|f(x) - f(y)\| \leq \alpha \|x - y\|, \forall x, y \in C.$$

Π_C denotes the set of all contractions on C . Note that f has a unique fixed point in C .

A mapping T of C into itself is called nonexpansive if $\|Tx - Ty\| \leq \|x - y\|$ for all $x, y \in C$. Denote by $F(T)$ the set of fixed points of T , that is, $F(T) = \{x \in C : Tx = x\}$.

Construction of fixed points of nonexpansive mappings is an important subject in the theory of nonexpansive mappings and its applications in a number of applied areas, in particular, in image recovery and signal processing (see, e.g., [1-2]).

An important approximation method for nonexpansive mappings is to consider the sequence $\{x_n\}$ generated by the algorithm:

$$x_{n+1} = t_n x_0 + (1 - t_n) T x_n, \quad n \geq 0, \quad (1.1)$$

where the initial point $x_0 \in C$ is taken arbitrarily and $\{t_n\}_{n=0}^{\infty}$ is a sequence in the interval $[0, 1]$. We call the iteration process (1.1) the Halpern iteration algorithm because of the introduction by Halpern^[3].

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The algorithm (1.1) has been proved to be strongly convergent in both Hilbert spaces^[3-4] and uniformly smooth Banach spaces^[5-7] unless the sequence $\{t_n\}$ satisfies the following conditions:

(A1) $t_n \rightarrow 0$; (A2) $\sum_{n=0}^{\infty} t_n = \infty$; (A3) either $\sum_{n=0}^{\infty} |t_n - t_{n+1}| < \infty$ or $\lim_{n \rightarrow \infty} (\frac{t_n}{t_{n+1}}) = 1$.

As mentioned in [8], the algorithm (1.1) has slow convergence due to the restriction of condition (A2). Moreover, it is shown in [3] that the conditions (A1) and (A2) are necessary, in the sense that if the algorithm (1.1) is always strongly convergent for all nonexpansive mappings from C into C , the conditions (A1) and (A2) must hold. So to improve the convergence rate of the algorithm (1.1), some additional steps have to be performed. For this purpose, Yanes and XU^[8] proposed the following CQ method:

$$\begin{cases} x_0 \in C, \text{ arbitrarily, } y_n = t_n x_0 + (1 - t_n)Tx_n, \\ C_n = \{v \in C : \|y_n - v\|^2 \leq \|x_n - v\|^2 + t_n(\|x_0\|^2 + 2\langle x_n - x_0, v \rangle)\}, \\ Q_n = \{v \in C : \langle x_n - v, x_n - x_0 \rangle \leq 0\}, x_{n+1} = P_{C_n \cap Q_n} x_0, \quad n \geq 0. \end{cases} \quad (1.2)$$

They proved the algorithm (1.2) has strong convergence under the condition (A1) only, which enhances the rate of convergence of the algorithm (1.1). More precisely, they proved the following theorem:

Theorem 1.1^[8] Let H be a real Hilbert space, and C be a closed convex subset of H . Let $T : C \rightarrow C$ be a nonexpansive mapping with $F(T) \neq \emptyset$. Assume that $\{t_n\} \subset (0, 1)$ satisfying (A1). Then the sequence $\{x_n\}$ generated by (1.2) converges strongly to $P_{F(T)}x_0$.

In 2004, XU^[9] studied the viscosity approximation algorithm for a nonexpansive mapping in a Hilbert space. More precisely, he proved the following theorem.

Theorem 1.2^[9] Let H be a real Hilbert space, and C be a closed convex subset of H . Assume that $T : C \rightarrow C$ is a nonexpansive mapping with $F(T) \neq \emptyset$ and $f \in \Pi_C$. Let $\{x_n\}$ be given by

$$x_0 \in C, \quad x_{n+1} = t_n f(x_n) + (1 - t_n)Tx_n, \quad n \geq 0. \quad (1.3)$$

Then under the conditions (A1)-(A3), $x_n \rightarrow x^*$, where x^* is the unique solution to the following variational inequality:

$$\langle (I - f)x^*, x - x^* \rangle \geq 0, \quad \forall x \in F(T). \quad (1.4)$$

Clearly, It is an important property of the viscosity approximation algorithm to select a particular fixed point of a given nonexpansive mapping which is the unique solution to the variational inequality (1.4).

It is obvious that if $f(x) \equiv x_0$ for all $x \in C$, then the viscosity approximation method (1.4) reduces to the Halpern iteration method (1.1). We note that the conditions on the control sequence $\{t_n\}$ in (1.3) are the same as those in (1.1). Hence, according to the analysis about the Halpern iteration method (1.1) in [8], the viscosity approximation algorithm (1.3) has slow convergence due to the restriction of the condition (A2).

For this reason, we will modify the viscosity approximation algorithm and construct a new iterative algorithm by the idea of (1.2) to remove the the restriction of the condition (A2).

2. Preliminaries

Let H be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and the induced norm $\|\cdot\|$, and let C be a nonempty, closed and convex subset of H . We write $x_n \rightarrow x$ to indicate that the

sequence $\{x_n\}$ converges weakly to x and $x_n \rightarrow x$ to indicate that the sequence $\{x_n\}$ converges strongly to x . We use $\omega_w(x_n) = \{x : \exists x_{n_j} \rightharpoonup x\}$ to denote the weak ω -limit set of $\{x_n\}$.

For each point $x \in H$, there exists a unique nearest point denoted by $P_C(x)$ in C , that is, $\|x - P_C(x)\| \leq \|x - y\|, \forall y \in C$.

The mapping $P_C : H \rightarrow C$ is called the metric projection of H onto C . It is well known that P_C is a nonexpansive mapping of H onto C , i.e.,

$$\|P_C(x) - P_C(y)\| \leq \|x - y\|, \quad \forall x, y \in H.$$

We recall some well known results which will be used in our analysis.

Lemma 2.1^[10] For given $x \in H$ and $y \in C$:

- (i) $y = P_C(x)$ if and only if $\langle x - y, z - y \rangle \leq 0, \forall z \in C$;
- (ii) $\|P_C(x) - z\|^2 \leq \|x - z\|^2 - \|x - P_C(x)\|^2, \forall z \in C$.

Lemma 2.2^[11] Let $\{x_k\}$ and $\{y_k\}$ be two bounded sequences in H , $\{\beta_k\}$ in $[0, 1]$.

Suppose that

$$\begin{cases} 0 < \liminf_{k \rightarrow \infty} \beta_k \leq \limsup_{k \rightarrow \infty} \beta_k < 1, x_{k+1} = (1 - \beta_k)y_k + \beta_k x_k, \\ \limsup_{k \rightarrow \infty} (\|y_{k+1} - y_k\| - \|x_{k+1} - x_k\|) \leq 0. \end{cases}$$

Then, $\lim_{k \rightarrow \infty} \|y_k - x_k\| = 0$.

3. A Modification of the Viscosity Approximation Method

Inspired by the results of [10-11], we propose the following Algorithm 3.1 to remove the restriction of the condition (A2) for finding a fixed point of a nonexpansive mapping.

Algorithm 3.1 Initialization. Choose $u \in C, x_0 \in C$, positive sequences $\{t_n\}, \{\beta_n\}, \{\gamma_n\}$ and $\{\epsilon_n\}$ such that

$$t_n + \beta_n + \gamma_n = 1, \lim_{n \rightarrow \infty} t_n = 0, \lim_{n \rightarrow \infty} \beta_n = \eta \in (0, 1), \text{ and } \sum_{n=0}^{\infty} \epsilon_n < \infty. \quad (3.1)$$

Step 1 Set $x_{n,1} := f(x_n)$.

Step 2 Inner loop $j = 1, 2, \dots$

Compute

$$\begin{cases} y_{n,j} := t_j x_{n,1} + (1 - t_j)T(x_{n,j}), \\ C_{n,j} = \{v \in C : \|y_{n,j} - v\|^2 \leq \|x_{n,j} - v\|^2 + t_j(\|x_{n,1}\|^2 + 2\langle x_{n,j} - x_{n,1}, v \rangle)\}, \\ Q_{n,j} = \{v \in C : \langle x_{n,j} - v, x_{n,j} - x_{n,1} \rangle \leq 0\}, \\ x_{n,j+1} = P_{C_{n,j} \cap Q_{n,j}}(x_{n,1}). \end{cases} \quad (3.2)$$

If $\|x_{n,j+1} - P_{F(T)}(x_{n,1})\| \leq \epsilon_n$, then set $h_n = x_{n,j+1}$ and go to Step 3. Otherwise, increase j by 1 and repeat the inner loop Step 2.

Step 3 Set $x_{n+1} := t_n u + \beta_n x_n + \gamma_n h_n$. Then increase n by 1 and go to Step 1.

Remark 3.1 By Theorem 1.1, we have $\{x_{n,j}\}$ generated by Step 2 of Algorithm 3.1 converges strongly to the point $P_{F(T)}(f(x_n))$ as $j \rightarrow \infty$. Consequently, we have that the inner loop in Algorithm 3.1 terminates after a finite number of steps.

Theorem 3.1 Let H be a real Hilbert space, and C be a closed convex subset of H . Let $T : C \rightarrow C$ be a nonexpansive mapping such that $F(T) \neq \emptyset$. Assume that $f : C \rightarrow C$ is an α -contraction. Then the sequence $\{x_n\}$ generated by Algorithm 3.1 converges strongly to $x^* \in F(T)$, where x^* is the unique solution to the variational inequality (1.4).

Proof By Lemma 2.1, we have that $x^* = P_{F(T)}f(x^*)$. Since P_C is nonexpansive and f is contractive, we have x^* is unique. Firstly, we observe that

$$\begin{aligned} & \|x_{n+1} - x^*\| \leq t_n \|u - x^*\| + \beta_n \|x_n - x^*\| + \gamma_n \|h_n - x^*\| \\ & \leq t_n \|u - x^*\| + \beta_n \|x_n - x^*\| + \gamma_n \|h_n - P_{F(T)}(f(x_n))\| + \gamma_n \|P_{F(T)}(f(x_n)) - P_{F(T)}f(x^*)\| \\ & \leq t_n \|u - x^*\| + \beta_n \|x_n - x^*\| + \gamma_n \epsilon_n + \gamma_n \alpha \|x_n - x^*\| \\ & \leq t_n \|u - x^*\| + \beta_n \|x_n - x^*\| + \gamma_n \epsilon_n + \gamma_n \|x_n - x^*\| \\ & = t_n \|u - x^*\| + (1 - t_n) \|x_n - x^*\| + \gamma_n \epsilon_n \\ & \leq \max\{\|u - x^*\|, \|x_0 - x^*\|\} + \sum_{n=0}^{\infty} \epsilon_n < \infty, \end{aligned}$$

which implies that $\{x_n\}$ is bounded, and hence, $\{h_n\}$ is also bounded. Next, we prove that $\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = 0$. We denote $x_{n+1} = \beta_n x_n + (1 - \beta_n)\xi_n$. Then, we have

$$\begin{aligned} \xi_{n+1} - \xi_n &= \frac{t_{n+1}u + \gamma_{n+1}h_{n+1}}{1 - \beta_{n+1}} - \frac{t_n u + \gamma_n h_n}{1 - \beta_n} \\ &= \left(\frac{t_{n+1}}{1 - \beta_{n+1}} - \frac{t_n}{1 - \beta_n}\right)u + \left(\frac{\gamma_{n+1}}{1 - \beta_{n+1}} - \frac{\gamma_n}{1 - \beta_n}\right)h_n + \frac{\gamma_{n+1}}{1 - \beta_{n+1}}(h_{n+1} - h_n). \end{aligned}$$

Thus, we get

$$\begin{aligned} & \|\xi_{n+1} - \xi_n\| - \|x_{n+1} - x_n\| \\ & \leq \left|\frac{t_{n+1}}{1 - \beta_{n+1}} - \frac{t_n}{1 - \beta_n}\right| \|u\| + \left|\frac{\gamma_{n+1}}{1 - \beta_{n+1}} - \frac{\gamma_n}{1 - \beta_n}\right| \|h_n\| + \frac{\gamma_{n+1}}{1 - \beta_{n+1}} \|h_{n+1} - h_n\| - \|x_{n+1} - x_n\| \\ & \leq \left|\frac{t_{n+1}}{1 - \beta_{n+1}} - \frac{t_n}{1 - \beta_n}\right| \|u\| + \left|\frac{\gamma_{n+1}}{1 - \beta_{n+1}} - \frac{\gamma_n}{1 - \beta_n}\right| (\|P_{F(T)}f(z_n)\| + \epsilon_n) - \|x_{n+1} - x_n\| \\ & + \frac{\gamma_{n+1}}{1 - \beta_{n+1}} (\|h_{n+1} - P_{F(T)}f(z_{n+1})\| + \|P_{F(T)}f(z_{n+1}) - P_{F(T)}f(z_n)\| + \|P_{F(T)}f(z_n) - h_n\|) \\ & \leq \left|\frac{t_{n+1}}{1 - \beta_{n+1}} - \frac{t_n}{1 - \beta_n}\right| \|u\| + \left|\frac{\gamma_{n+1}}{1 - \beta_{n+1}} - \frac{\gamma_n}{1 - \beta_n}\right| (\|P_{F(T)}f(z_n)\| + \epsilon_n) \\ & + \frac{\gamma_{n+1}}{1 - \beta_{n+1}} (\epsilon_{n+1} + \epsilon_n) + \frac{\gamma_{n+1}}{1 - \beta_{n+1}} \|x_{n+1} - x_n\| - \|x_{n+1} - x_n\| \\ & \leq \left|\frac{t_{n+1}}{1 - \beta_{n+1}} - \frac{t_n}{1 - \beta_n}\right| \|u\| + \left|\frac{\gamma_{n+1}}{1 - \beta_{n+1}} - \frac{\gamma_n}{1 - \beta_n}\right| (\|P_{F(T)}f(z_n)\| + \epsilon_n) \\ & - \frac{t_{n+1}}{1 - \beta_{n+1}} \|x_{n+1} - x_n\| + \frac{\gamma_{n+1}}{1 - \beta_{n+1}} (\epsilon_{n+1} + \epsilon_n). \tag{3.3} \end{aligned}$$

From the assumptions in (3.1) and the boundness of $\{x_n\}$, it follows that

$$\limsup_{n \rightarrow \infty} (\|\xi_{n+1} - \xi_n\| - \|x_{n+1} - x_n\|) \leq 0.$$

Now applying Lemma 2.2, we have

$$\lim_{n \rightarrow \infty} \|\xi_n - x_n\| = 0. \tag{3.4}$$

By $x_{n+1} = \beta_n x_n + (1 - \beta_n)\xi_n$, we obtain that

$$\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = \lim_{n \rightarrow \infty} (1 - \beta_n) \|\xi_n - x_n\| = 0. \tag{3.5}$$

We observe that

$$\begin{aligned} \|P_{F(T)}f(x_n) - x_{n+1}\| & \leq t_n \|P_{F(T)}f(x_n) - u\| + \beta_n \|P_{F(T)}f(x_n) - x_n\| + \gamma_n \|P_{F(T)}f(x_n) - h_n\| \\ & \leq t_n \|P_{F(T)}f(x_n) - u\| + \beta_n \|P_{F(T)}f(x_n) - x_n\| + \gamma_n \epsilon_n. \end{aligned} \tag{3.6}$$

Consequently, from (3.6), we have

$$\begin{aligned} \|P_{F(T)}f(x_n) - x_n\| &\leq \|P_{F(T)}f(x_n) - x_{n+1}\| + \|x_{n+1} - x_n\| \\ &\leq (t_n\|P_{F(T)}f(x_n) - u\| + \beta_n\|P_{F(T)}f(x_n) - x_n\| + \gamma_n\epsilon_n) + \|x_{n+1} - x_n\|, \end{aligned}$$

which implies that

$$(1 - \beta_n)\|P_{F(T)}f(x_n) - x_n\| \leq t_n\|P_{F(T)}f(x_n) - u\| + \gamma_n\epsilon_n + \|x_{n+1} - x_n\|.$$

Since $\lim_{n \rightarrow \infty} t_n = 0$, $\lim_{n \rightarrow \infty} \epsilon_n = 0$ and $\lim_{n \rightarrow \infty} \beta_n = \eta \in (0, 1)$, it follows from (3.5) that

$$\lim_{n \rightarrow \infty} \|P_{F(T)}f(x_n) - x_n\| = 0. \quad (3.7)$$

Since

$$\begin{aligned} \|x_n - x^*\| &\leq \|x_n - P_{F(T)}f(x_n)\| + \|P_{F(T)}f(x_n) - P_{F(T)}f(x^*)\| \\ &\leq \|x_n - P_{F(T)}f(x_n)\| + \alpha\|x_n - x^*\|, \end{aligned}$$

we have that $(1 - \alpha)\|x_n - x^*\| \leq \|x_n - P_{F(T)}f(x_n)\| \rightarrow 0$, as $n \rightarrow \infty$. This shows that $x_n \rightarrow x^*$, as $n \rightarrow \infty$.

Remark 3.2 Theorem 3.1 improves Theorem 3.2 in [9] (i.e. Theorem 1.2 in this paper) in the following sense:

The condition (A2) is removed. Algorithm 3.1 converges strongly to the unique solution of the variational inequality (1.4) under only the condition (A1).

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Hilbert空间中关于不动点问题粘滞逼近法的一个修正

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摘要: 本文对Hilbert空间中关于非扩张映射不动点问题的粘滞逼近法提出一个修正, 该修正后的算法取消了粘滞逼近法中的一个控制条件, 并建立了该算法的一个强收敛定理.

关键词: 非扩张映射; 度量投影; 不动点; 压缩; 粘滞逼近法